

- Clásica  $\rightarrow$  Puntos con sus imágenes
- No Clásicas  $\rightarrow$  Puntos o derivadas en puntos y sus imágenes

Hermite  $\left\{ \begin{array}{l} \text{Puntos} \\ \text{Imágenes de Puntos} \\ \text{Derivadas en Puntos} \end{array} \right.$  1ª Parcial

$$p(x) = a_0 + a_1 x + a_2 x^2 + \dots + a_{2n+1} x^{2n+1}$$

$$p'(x) = a_1 + 2a_2 x + \dots + (2n+1)a_{2n+1} x^{2n}$$

• Taylor  $\rightarrow x_0, f(x_0), f'(x_0), f''(x_0), \dots$

## ① CLÁSICA O DE LAGRANGE

Soporte  $\Rightarrow S = \{x_0, x_1, \dots, x_n\} \rightarrow$  Imágenes  $\rightarrow n+1$  datos  $\rightarrow$  podemos resolver  $n+1$  condiciones  $\rightarrow$  max grado  $n$   
 $\mathcal{P}_n \equiv$  Espacio vectorial de los polinomios de grado  $\leq n \rightarrow \dim \mathcal{P}_n = n+1$   
 Si  $n^\circ$  Condiciones =  $\dim$  espacio  $\rightarrow$  Sol. es única.

• Determinante de Van der Monde

$$\Delta = \begin{vmatrix} 1 & x_0 & x_0^2 & \dots & x_0^n \\ 1 & x_1 & x_1^2 & \dots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^n \end{vmatrix}$$

$\Delta \neq 0 \rightarrow \exists$  Sol. y es única

$\Delta = 0 \rightarrow \begin{cases} R_i \Delta \neq R_j \Delta \rightarrow \text{No Sol.} \rightarrow \text{Sistema incompatible} \\ R_i \Delta = R_j \Delta \rightarrow \infty \text{ Sol.} \rightarrow \text{Compatible indeterminado} \end{cases}$

## ② POLINOMIO DE LAGRANGE

Sea  $f(x)$  definida por  $\{x_0, x_1, \dots, x_n\}$  Tomando  $x_i \neq x_j \quad i \neq j$

• Polinomio  $i$ -ésimo  $\rightarrow$  Polinomio  $\ell_i$  de grado no superior a  $n$ , tal que en  $x_i$  del soporte tiene valor 1 y en todos los demás 0.  $\rightarrow \ell_i(x_j) = 1, \ell_i(x_j) = 0 \quad i \neq j$

$$\ell_i(x) = \prod_{\substack{j=0 \\ j \neq i}}^n \frac{x - x_j}{x_i - x_j} \rightarrow \text{Polinomio de Lagrange} \rightarrow \text{Base de Lagrange} \rightarrow \mathcal{B} \{ \ell_0, \dots, \ell_n \}$$

$$p_n(x) = f(x_0)\ell_0(x) + \dots + f(x_n)\ell_n(x) = \sum_{i=0}^n f(x_i)\ell_i(x) \rightarrow \text{Fórmula de Lagrange para el caso de interpolación clásica}$$

## ③ POLINOMIAL DE TAYLOR

$x_0 \in \mathbb{R}, f \in C^n([x_0, y])$  Entonces  $p \in \mathcal{P}_n / p^{(i)}(x_0) = f^{(i)}(x_0) \quad i = 0, \dots, n$

## ④ BASE DE LAGRANGE

$B = \{\ell_0, \ell_1, \dots, \ell_n\} \rightarrow$  Cumpliendo  $\ell_i(x_j) = \begin{cases} 1 & \text{si } i=j \\ 0 & \text{si } i \neq j \end{cases}$

$$V = \sum_{i=0}^n x_i \ell_i \rightarrow \ell_0(x) = z_0, \ell_1(x) = z_1, \ell_2(x) = z_2$$

$$x_0 = z_0, x_1 = z_1, x_2 = z_2$$

$$V = z_0 \ell_0 + z_1 \ell_1 + z_2 \ell_2$$

## ⑤ Error de interpolación

$$|E(x)| = |p_n(x) - f(x)| \quad x \in [a, b] \rightarrow \frac{|f^{(n+1)}(\xi)|}{(n+1)!} |(x-x_0)(x-x_1)\dots(x-x_n)|$$

## ⑥ BASE DE NEWTON, POLINOMIO DE NEWTON Y DIFERENCIAS DIVIDIDAS

• Base de Newton  $\rightarrow \{1, x-x_0, (x-x_0)(x-x_1), \dots, [(x-x_0)(x-x_1)\dots(x-x_{n-1})]\}$

$\Delta = |\mathcal{N}| \rightarrow$  Diagonal principal  $\neq 0 \quad (x_i \neq x_j \quad \forall j, i) \Rightarrow \exists$  Sol. y es única

• Polinomio de Newton

Clásico  $\rightarrow p_n(x) = f(x_0) + f[x_0, x_1](x-x_0) + \dots + f[x_0, x_1, \dots, x_n] [(x-x_0)(x-x_1)\dots(x-x_{n-1})]$

• Diferencias

Divididas  $\rightarrow f[x_0] = f(x_0) \rightarrow f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0} \rightarrow [x_0, x_1, x_2] = \frac{f[x_0, x_1] - f[x_1, x_2]}{x_0 - x_2}$

$$* f[x_0, x_0, x_0] = \frac{f^{(2)}(x_0)}{2!} \Rightarrow \text{la utilización de Newton para casos no clásicos (Taylor, Hermite)}$$

$3n-1$

Grado 2  $\Rightarrow 1 \text{ Lib}$

Grados  $\Rightarrow 2 \text{ Lib}$

Optimización

$4n-2$

Grado  $m \rightarrow \psi_{[x_0, x_1, x_2]}$  es un polinomio de grado  $m$ .  $\rightarrow \psi \in C^{m-1}$  (Tiene  $m-1$  derivadas continuas)

Exigir  $\rightarrow$  Continuidad de  $\psi(x)$  ( $n-1$  condiciones)  $\rightarrow$  Continuidad de  $\psi'$  ( $n-1$  condiciones)  $\rightarrow$  cond. interpolación ( $n+1$  condiciones)

• Cubicos Naturales  $\Rightarrow S''(x_0) = S''(x_n) = 0 \rightarrow$  Como tenemos  $z_0$  y  $z_n \rightarrow \delta_i = x_i - x_{i+1} \rightarrow y_i =$  Imagen en  $i$

es recta

$$\frac{x-x_0}{x_1-x_0} = \frac{y-y_0}{y_1-y_0}$$

$$\frac{\delta_i}{6} z_{i-2} + \frac{\delta_i - \delta_{i+1}}{3} z_{i-1} + \frac{\delta_{i+1}}{6} z_{i+1} = \frac{y_{i-1}}{\delta_i} - \left( \frac{1}{\delta_i} + \frac{1}{\delta_{i+1}} \right) y_i + \frac{y_{i+1}}{\delta_{i+1}} \Rightarrow \text{obtener } z_i$$

$$S(x) = \frac{z_{i-1}}{6\delta_i} (x_i - x)^3 + \frac{z_i}{6\delta_i} (x - x_{i-1})^3 + \left( \frac{y_i}{\delta_i} - \frac{z_i \delta_i}{6} \right) (x - x_{i-1}) + \left( \frac{y_{i-1}}{\delta_i} - \frac{z_{i-1} - \delta_i}{6} \right) (x_i - x)$$

## MÉTODO DE APROXIMACIÓN

Dist  $\rightarrow d((x_1, y_1), (x_2, y_2)) = |x_1 - x_2| + |y_1 - y_2|$ ; Dist Euclídea  $\rightarrow d((x_1, y_1), (x_2, y_2)) = \sqrt{(x_1 - x_2)^2 + (y_1 - y_2)^2}$

i)  $d(x, y) \geq 0 \quad \forall x, y \in E$

ii)  $d(x, y) = d(y, x)$

iii)  $d(x, y) \leq d(x, z) + d(y, z) \quad \forall x, y, z \in E$

Desigualdad triangular

Dist  $(E, d) \rightarrow$  Espacio Métrico

i)  $\|x\| \geq 0; \|x\| = 0 \Leftrightarrow x = 0$

ii)  $\|\lambda x\| = |\lambda| \|x\| \quad \forall \lambda \in \mathbb{R}, x \in E$

iii)  $\|x + y\| \leq \|x\| + \|y\| \quad \forall x, y \in E$

(E,  $\|\cdot\|$ )  $\rightarrow$  Espacio Normado

$\langle x, y \rangle = \langle y, x \rangle \quad \forall x, y \in E$

ii)  $\langle \alpha x_1 + \beta x_2, y \rangle = \alpha \langle x_1, y \rangle + \beta \langle x_2, y \rangle$

iii)  $\langle x, x \rangle \geq 0 \Leftrightarrow x = 0$

• Toda norma induce a una distancia:

$d(x, y) = \|x - y\| \rightarrow$  Todo espacio métrico es un espacio normado

$\|x\| = \sqrt{\langle x, x \rangle} \quad d(x, y) = \|x - y\| = \sqrt{\langle x - y, x - y \rangle}$



- Producto escalar  $\rightarrow \langle f, g \rangle = \int_a^b f(x)g(x) dx$  • Norma  $\|f\| = \sqrt{\langle f, f \rangle} = \sqrt{\int_a^b f(x)f(x) dx} \rightarrow \|g\| = \left(\int_a^b g^2(x) dx\right)^{1/2}$
- Distancia  $\rightarrow d(f, g) = \|f - g\| = \left(\int_a^b (f(x) - g(x))^2 dx\right)^{1/2}$   $\rightarrow$  Mejor aproximación  $\Rightarrow d(u, f) \leq d(v, f) \quad \forall v \in H$
- $u \in H$  es mejor aprox de  $f$  en  $H \iff \langle f - u, v \rangle = 0 \quad \forall v \in H$

- Proceso de GRAM-SCHMIDT  $\rightarrow \tilde{V}_k = V_k - \frac{\langle V_k, \tilde{V}_1 \rangle}{\langle \tilde{V}_1, \tilde{V}_1 \rangle} \tilde{V}_1 - \dots - \frac{\langle V_k, \tilde{V}_{k-1} \rangle}{\langle \tilde{V}_{k-1}, \tilde{V}_{k-1} \rangle} \tilde{V}_{k-1}$   $B = \{\tilde{V}_1, \tilde{V}_2, \dots, \tilde{V}_n\}$   
 $\tilde{B} = \{\tilde{V}_1, \tilde{V}_2, \dots, \tilde{V}_n\}$

### • BASE ORTOGONAL

$f, g \in E$  ortogonales  $\rightarrow \langle f, g \rangle = 0 \Rightarrow U(x) = \alpha_1 \tilde{V}_1 + \alpha_2 \tilde{V}_2 + \dots + \alpha_n \tilde{V}_n \rightarrow \alpha_1 \langle \tilde{V}_1, \tilde{V}_1 \rangle = \langle f, \tilde{V}_1 \rangle, \dots, \alpha_n \langle \tilde{V}_n, \tilde{V}_n \rangle = \langle f, \tilde{V}_n \rangle$

$$\alpha_i = \frac{\langle f, \tilde{V}_i \rangle}{\langle \tilde{V}_i, \tilde{V}_i \rangle} = \frac{\langle f, \tilde{V}_i \rangle}{\|\tilde{V}_i\|^2}$$

$$U(x) = \sum_{i=1}^n \alpha_i \tilde{V}_i = \sum_{i=1}^n \frac{\langle f, \tilde{V}_i \rangle}{\|\tilde{V}_i\|^2} \tilde{V}_i$$

$\Rightarrow$  Mejor Aproximación con Base Ortogonal

### • BASE ORTONORMAL

①  $\rightarrow$  Ortogonal:  $\langle \tilde{V}_i, \tilde{V}_j \rangle = 0 \quad i \neq j$ ; ②  $\rightarrow$  Norma=1:  $\forall i \|\tilde{V}_i\| = 1; \|\tilde{V}_i\|^2 = \langle \tilde{V}_i, \tilde{V}_i \rangle \Rightarrow \langle \tilde{V}_i, \tilde{V}_i \rangle = 1 \quad i, j = 1, \dots, n$

$$U(x) = \sum_{i=1}^n \langle f, \tilde{V}_i \rangle \tilde{V}_i \Rightarrow \text{Mejor aproximación con Base Ortonormal}$$

$\rightarrow$  Suma de Fourier para  $f$ .  $\langle f, \tilde{V}_i \rangle$  coeficiente de Fourier.

$$\begin{aligned} \text{Si } \|\tilde{V}_i\| &= 1 \\ \langle \tilde{V}_i, \tilde{V}_i \rangle &= 1 \\ \text{Si } \langle \tilde{V}_1, \tilde{V}_2 \rangle &= 0 \\ \langle \tilde{V}_1, \tilde{V}_2 \rangle &= 0 \end{aligned}$$

### • CÁLCULO DE $U(x)$

1. Seleccionar una Base
- ii)  $\langle f - u, \tilde{V}_1 \rangle = \langle f - u, \tilde{V}_2 \rangle = \dots = \langle f - u, \tilde{V}_n \rangle = 0$
- iii)  $\langle u, \tilde{V}_i \rangle = \langle f, \tilde{V}_i \rangle \quad i = 1, \dots, n$
- iv)  $U(x) = \alpha_1 \tilde{V}_1 + \alpha_2 \tilde{V}_2 + \dots + \alpha_n \tilde{V}_n$
- v) Sustituimos  $U(x)$  en (iii)
- vi) Calculamos cada  $\alpha_i$

2. Seleccionar  $B = \{\tilde{V}_1, \tilde{V}_2, \dots, \tilde{V}_n\}$  y expresar  $\tilde{B} = \{\tilde{V}_1, \tilde{V}_2, \dots, \tilde{V}_n\}$
- ii) Dar valores a  $\tilde{V}_i$  y sacar  $\langle \tilde{V}_1, \tilde{V}_2 \rangle = 0$ . Con  $\tilde{V}_i = \alpha_{i1} \tilde{V}_1 + \alpha_{i2} \tilde{V}_2 + \dots + \alpha_{in} \tilde{V}_n$
- iii) Con el paso (ii) obtengo todos los  $\tilde{V}_i$
- iv) Con una base ortogonal generica (iii), forzamos  $\langle \tilde{V}_i, \tilde{V}_i \rangle = 1; \|\tilde{V}_i\| = 1$
- v)  $\tilde{V}_i \rightarrow \langle f - u, \tilde{V}_i \rangle = 0$ . Con  $U(x) = \alpha \tilde{V}_1 + \beta \tilde{V}_2 + \dots$
- vi) Calculamos  $\alpha, \beta, \dots$

### ③ Mínimos cuadrados

Continuo  $\begin{cases} \text{a) } d(f, g) = \int_a^b (f(x) - g(x))^2 w(x) dx \\ \text{b) } \langle f, g \rangle = \int_a^b f(x)g(x)w(x) dx \\ \text{c) } \|f\|^2 = \int_a^b f^2(x)w(x) dx \end{cases}$

Discreto  $\begin{cases} \text{a) } d(f, g) = \|f - g\| = \left(\sum_{i=1}^n (f_i - g_i)^2 w_i\right)^{1/2} \\ \text{b) } \langle f, g \rangle = \sum_{i=1}^n f_i g_i w_i \\ \text{c) } \|f\|^2 = \sum_{i=1}^n f_i^2 w_i \end{cases}$

$U(x) = c f(x)$

$w(x) \rightarrow$  Función Pso  
 $w(x) \geq 0 \quad \forall x$

$w = (w_1, \dots, w_n)$   
 Dim = no vectores  $\Rightarrow (v_1, v_2)$   
 Si  $y = Ax + B \Rightarrow \Delta \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + B \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$   
 (vi)  $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} - B \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

### • ERROR DE MEJOR APROXIMACIÓN

$$|e| = \|f - u\| = \sqrt{\|f\|^2 - \|u\|^2}$$

$$U(x) \text{ m.a.} \iff \langle f - u, \tilde{V}_i \rangle = 0$$

### FUNCIONES NO LINEALES

1. Polinomio  $\rightarrow$   $f(a) f(b) < 0 \Rightarrow S \in [a, b]$
2. Unicidad  $\rightarrow \exists f(x) \neq 0 \Rightarrow S$  es Única en  $[a, b]$

Completo Dy  $\begin{cases} \text{Discreción} \\ x_0 = \frac{a+b}{2} \\ |e_n| \leq \frac{b-a}{2^{n+1}} \end{cases}$

• REGULA FALSI  
 $x_0 = \frac{a f(b) - b f(a)}{f(b) - f(a)}; \quad x_n = \frac{x_{n-1} f(b) - b f(x_{n-1})}{f(b) - f(x_{n-1})}$   
 $|e_n| = |x_n - x_{n-1}| \leq \epsilon \rightarrow$  Concluido

### • SECANTE

$x_0 = a, x_1 = b$   
 $x_n = \frac{x_{n-2} f(x_{n-1}) - x_{n-1} f(x_{n-2})}{f(x_{n-1}) - f(x_{n-2})}$   
 ii) SECANTE NO ASEGURA CONVERGENCIA!

### LINEALES

$$d_1 = \sum_{i=1}^n |x_i - y_i|$$

$$d_2 = \sqrt{\sum_{i=1}^n |x_i - y_i|^2}$$

$$d_\infty = \max |x_i - y_i|$$

$$d_1(g(x), g(y)) = |g(x) - g(y)|$$

$$d_2(g(x), g(y)) = \sqrt{|g(x) - g(y)|^2}$$

$$d_\infty(g(x), g(y)) = \max |g(x) - g(y)|$$

$$\|x\|_1 = \sum_{i=1}^n |x_i|$$

$$\|x\|_2 = \sqrt{\sum_{i=1}^n |x_i|^2}$$

$$\|x\|_\infty = \max |x_i|$$

- Aplicación contractiva  
 $d(g(x), g(y)) = |g(x) - g(y)| \leq K |x - y| \quad K < 1$
- Punto fijo de Aplicación Contractiva  
 $x = f(x) \iff x = cte \Rightarrow Pto. fijo$

Problema del Punto Fijo  $\rightarrow$  Si  $g(x)$  es contractiva en un espacio métrico completo  $\Rightarrow \exists s$  y es único. Además ese punto fijo es el l.m de la sucesión  $s = g(x_n) / s = \lim_{n \rightarrow \infty} x_n$ . Empezando en  $x_0$  arbitrario

### CONVERGENCIA GLOBAL

Si  $g$  creciente  $|g(a)| \leq b$

Si  $g$  decrece  $\begin{cases} x_0 \in [a, b] \\ g(a) \leq b \\ g(b) \geq a \end{cases}$

### CONVERGENCIA LOCAL

$\rightarrow$  ① Si  $\exists$  tal que  $s = g(s)$  y  $g(x) \in C^1[a, b]$  ②  $|g'(x)| < 1$

### ERROR EN LINEALES ITERATIVOS

$$|e_n| = |x_n - s| \leq \frac{L^n |x_1 - x_0|}{1 - L}; \quad L = \max |g'(x)| \text{ en } [a, b]$$

### CONVERGENCIA LINEAL

$$\lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|} = |g'(s)| \neq 0$$

Dem.

$x_0, x_1 = g(x_0), x_2 = g(x_1), x_{n+1} = g(x_n)$   
 $\rightarrow$  Desarrollo por Taylor

$$g(x_n) = g(s) + g'(s)(x_n - s) \text{ con } s \in [x_n, x_1]$$

$$x_{n+1} - s = g'(s)(x_n - s) \Rightarrow \frac{|x_{n+1} - s|}{|e_n|} = |g'(s)| \frac{|x_n - s|}{|e_n|}$$

$$|e_{n+1}| = |g'(s)| |e_n| \Rightarrow \frac{|e_{n+1}|}{|e_n|} = |g'(s)| \rightarrow \epsilon \neq cte \rightarrow n \text{ a los } ①$$

### GRADOK

$$S = g(s) \quad g'(s) = g''(s) = \dots = g^{(k-1)}(s) = 0$$

$$g^{(k)}(s) \neq 0 \quad \lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^k} = \frac{g^{(k)}(s)}{k!} \neq 0$$

Newton-Raphson  $\rightarrow$  Se necesita convergencia local  $\rightarrow x_n = x_{n-1} - \frac{f(x_{n-1})}{f'(x_{n-1})}$

• Condiciones de convergencia:

- ①  $f(x) \in C^2 \Rightarrow$  Continua de orden 2 ② Bolzano  $f(a)f(b) < 0$  ③  $f'(x)_{[a,b]} \neq 0 \nexists !s$  ④  $f''(x)_{[a,b]} \neq 0$

Comienzo a iterar con  $x_0 \approx s$  que cumple

- ⑤  $f(x_0)f'(x_0) > 0 \Rightarrow$   $\exists$  convergencia N-R ⑥  $\exists$  conv si  $\max \left| \frac{f(x)}{f'(x)}, \frac{f'(x)}{f''(x)} \right| \leq b-a$  ⑦ si  $f(x) \in C^3$  al menos cuadrática

• Cota de Error

$$|e_n| = |x_n - s| \leq \frac{M |x_n - x_{n-1}|^2}{2m}; M = \max |f''(x)|_{[a,b]}; m = \min |f'(x)|_{[a,b]}$$

• Orden de Convergencia

$$\lim_{n \rightarrow \infty} \frac{|e_{n+1}|}{|e_n|^2} = \frac{f''(s)}{2f'(s)} = cte \neq 0$$

RAÍCES MÚLTIPLES  $\rightarrow$  Si  $s_1 = s_2 = \dots = s_n \rightarrow x_n = x_{n-1} - p \frac{f(x)}{f'(x)}$

$\downarrow$   
Si  $s_1 \neq s_2 \rightarrow$  Métodos sustitutivos

① WILKINSON

$$x_n = x_{n-1} - \frac{f(x)}{m}$$

$m =$  orden de magnitud de  $f(x)_{[a,b]}$

② M-R MODIF

$$x_n = x_{n-1} - \frac{f(x_{n-1})}{f'(x_0)}$$

③ Secante

$$x_n = \frac{x_{n-2}f(x_{n-1}) - x_{n-1}f(x_{n-2})}{f(x_{n-1}) - f(x_{n-2})}$$

EJERCICIOS Y EJEMPLOS  $\rightarrow$  Identidad de Parseval  $\Rightarrow \langle f, g \rangle = \sum_{i=1}^n \langle f, u_i \rangle \langle g, u_i \rangle$ ; con B ortogonal

$$\left. \begin{aligned} f(x) &= a_1 u_1(x) + a_2 u_2(x) + \dots + a_n u_n(x) \\ g(x) &= b_1 u_1(x) + b_2 u_2(x) + \dots + b_n u_n(x) \end{aligned} \right\}, x \in [0, \pi/2] \Rightarrow \sum_{i=1}^n \sum_{j=1}^n a_i b_j \langle u_i, u_j \rangle = \sum_{i=1}^n \sum_{j=1}^n a_i b_j \delta_{ij} = \sum_{i=1}^n a_i b_i$$

$$= \sum_{i=1}^n \sum_{j=1}^n a_i b_j \delta_{ij} = \sum_{i=1}^n a_i b_i \quad \left\{ \begin{aligned} \langle f, u_k \rangle &= \sum_{i=1}^n a_i \langle u_i, u_k \rangle = a_k \\ \langle g, u_k \rangle &= \sum_{i=1}^n b_i \langle u_i, u_k \rangle = b_k \end{aligned} \right\} \Rightarrow \sum_{i=1}^n \langle f, u_i \rangle \langle g, u_i \rangle$$

- me dan  $u(x)$  m.a. y  $f(x) \rightarrow u(x) \Rightarrow a = \frac{\langle f, x \rangle}{\|x\|^2}$

$$\int_0^{\pi/2} x \sin x dx = 1 \quad \|x\|^2 = \langle x, x \rangle = \int_0^{\pi/2} x^2 dx$$



Dominante en la diagonal  $\rightarrow |a_{ii}| > \sum_{j \neq i} a_{ij}$  Def.  $\oplus \Rightarrow L$  de  $B$  de terminantes  $|B| > 0$  Simétrica  $\oplus \Rightarrow x^T A x = 0 \Rightarrow x = 0$   
 Espectro Matriz  $\rightarrow$  Conjunto de autovalores  $\sigma(A) = \{\lambda_i(A)\}$  Radio espectral  $\rightarrow \rho(A) = \max_i |\lambda_i(A)|$   $\rho(A) \leq \|A\|$  Semisimétrica  $\oplus \Rightarrow x \neq 0$

- Norma de vector  
 $\|x\|_1 = \sum_{i=1}^n |x_i|$   
 $\|x\|_2 = \left[ \sum_{i=1}^n |x_i|^2 \right]^{1/2}$   
 $\|x\|_\infty = \max_i |x_i|$   $\forall x \in \mathbb{R}^n$
- Norma de una matriz  
 $\|A\|_1 = \max_j \sum_i |a_{ij}|$  (columnas)  
 $\|A\|_2 = \sqrt{\lambda_{\max}(A^T A)}$   
 $\|A\|_\infty = \max_i \sum_j |a_{ij}|$  (filas)
- Condicionamiento de una matriz  
 $\kappa(A) = \|A\| \|A^{-1}\| \Rightarrow \kappa = 1 \oplus$   
 $\kappa > 1$  mal, si  $> 1000$
- Resolución progresiva  
 $x_1 = \frac{b_1}{a_{11}}$   $x_i = \frac{b_i - \sum_{j=1}^{i-1} a_{ij} x_j}{a_{ii}}$   
 $Lx = b$
- Resolución regresiva  
 $x_n = \frac{b_n}{a_{nn}}$   $x_i = \frac{b_i - \sum_{j=i+1}^n a_{ij} x_j}{a_{ii}}$   
 $Ux = b$

**GAUSS**  $\oplus a_{ii} \neq 0$ , si no  $E_i \leftrightarrow E_j$   
 ①  $a_{ii} \neq 0$   
 ②  $m_{ij} = \frac{a_{ij}}{a_{ii}}$   $E_i' = E_i - m_{ij} E_j$   
 ③ Repetir hasta  $U$   
 Sol  $\star$   
 $x_n = \frac{b_n}{a_{nn}}$   $x_i = \frac{b_i - \sum_{j=i+1}^n a_{ij} x_j}{a_{ii}}$

**GAUSS-JORDAN**  
 ①  $|A| \neq 0$   
 $\Delta x = b \rightarrow \Delta x = b^*$  Sol  $\Rightarrow x_i = \frac{b_i}{a_{ii}}$   
 ②  $y = 0$   
 ③  $m_{ij} = \frac{a_{ij}}{a_{ii}}$   $E_i' = E_i - m_{ij} E_j$   
 ④ Repetir

**PIVOTAGE**  
 • PARCIAL  $\max_{k \in I} |a_{kj}|$   $i \in I, r \in n$   
 $E_i \leftrightarrow E_j$   
 • TOTAL  $\max_{i \in I, j \in J} |a_{ij}|$   $i \in I, j \in J$   
 - Filas y columnas no tratadas  
 - permuta de fila y columna  
 - permuta de  $b$  y  $a_{ii}$  Sol !!

**TRID. G. U. D. L.**  
 $\Delta = LU$   $U u_i = 1 \Rightarrow$  CROUT  
 $\Delta \Rightarrow LU \Rightarrow L U x = b \rightarrow L y = b \rightarrow y$   
 $L y = b \rightarrow U x = y \rightarrow x$

**DOOLITTLE**  
 ① 1ª fila de  $L \times U$   
 ②  $(L^{-1} \text{ fila}) \times (U \text{ columna})$   
 ③ 2ª fila de  $L \times U$   
 ④  $(L^{-1} y \text{ 2ª fila}) \times (U \text{ columna})$   
 ⑤ 3ª fila de  $L \times U$  ( $L^{-1} y \text{ 3ª columna}$ )  
 ⑥  $Ly = b$ ,  $Ux = y$

**CROUT**  
 $u_{ii} = 1$ ,  $e_{ii} \neq 0$   
 $|A| \neq 0$   
 Cambio  $U \times b$   
 $y$  es doolittle  
 pero con column  $\leftrightarrow$  fila

**$\Delta = \Delta^T$**   
 $\Delta = L \Delta^T L^T = LU / (u_{ii} = 1)$   
 Doolittle

**CHOLESKY** Condiciones  $\rightarrow \Delta = \Delta^T$   
 Def  $\oplus$   
 ① 1ª fila de  $L \times L^T$   
 ② 2ª fila de  $L \times L^T$  ( $L^{-1} \text{ columna}$ )  
 ③ 3ª fila de  $L \times L^T$  ( $L^{-1} y \text{ columna}$ )  
 ④  $Ly = b$ ,  $Ux = y$   
 ⑤  $|A| = \prod_{i=1}^n u_{ii}$

**DOO  $\rightarrow$  CROUT**  
 $U \Rightarrow DU^T / u_{ii} = 1 \rightarrow \Delta = L DU^T = L U^T / u_{ii} = 1$   
 $U \Rightarrow DU^T / u_{ii} = 1 \rightarrow \Delta = L DU^T = L U^T / u_{ii} = 1$

**DOO  $\rightarrow$  CHOLESKY** Cond. de Cholesky  
 $U \Rightarrow DU^T / u_{ii} = 1 \rightarrow \Delta = L DU^T = L U^T / u_{ii} = 1$   
 $\Delta = L U^T$

**COTAS**  
 $b) \frac{\|r\|}{\|K(A)\| \|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|}$   
 $\frac{\|r\|}{\|K(A)\| \|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|}$   
 $\frac{\|r\|}{\|K(A)\| \|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|} \leq \frac{\|K(A)\| \|r\|}{\|b\|}$

**ITERATIVOS**  
 $Ax = b \rightarrow Ax + x = b + x \rightarrow (A+I)x = b+x \rightarrow x = (A+I)^{-1} (b+x)$   
 $x = Bx + C$   
 $x^{n+1} = Bx^n + C$   
 $x^{n+1} = M^{-1} N x^n + M^{-1} b$   
 $x^{n+1} = M^{-1} N x^n + M^{-1} b$

**JACOBI**  
 $x^{n+1} = D^{-1} (Lx^n + Ux^n + b)$   
 $\Delta = D - L - U$   $C_j = D^{-1} b$   
 $M = D$   $N = L + U$   $B_j = D^{-1} L$   $C_j = D^{-1} b$   
 $x_i^{n+1} = \frac{b_i - \sum_{j \neq i} a_{ij} x_j^n}{a_{ii}}$   $i = 1, 2, \dots, n$

**GAUSS-SEIDEL**  
 $x^{n+1} = (D-L)^{-1} Ux^n + (D-L)^{-1} b$   
 $M = D - L$   $N = U$   $B = (D-L)^{-1} U$   $C = (D-L)^{-1} b$   
 $x_i^{n+1} = \frac{b_i - \sum_{j < i} a_{ij} x_j^{n+1} - \sum_{j > i} a_{ij} x_j^n}{a_{ii}}$

**W-BZ**  
 $w = 1 \rightarrow$  GS  $< 1$  SUB  $> 1$  sobre  
 $\Delta = D - L - U \Rightarrow \Delta = D - L - U$   
 $\Delta x = w(b + Lx^n + Ux^n) + (1-w) \Delta x^n \Rightarrow$  Exp. matricial  
 $x_i^{n+1} = \frac{w}{a_{ii}} \left( b_i - \sum_{j \neq i} a_{ij} x_j^n \right) + (1-w) x_i^n$

**CONV**  $\oplus$  Dom diagonal  $\|B\| = \max_i \sum_j |b_{ij}| < 1$   
 ①  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ②  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ③  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
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 ⑧  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑨  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑩  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑪  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑫  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑬  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ⑭  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
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 ⑳  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
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 ㉒  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ㉓  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
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 ㊾  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$   
 ㊿  $\Delta = \Delta^T$   $\oplus$  Trid. diagonal  $(\rho(B_j))^2 = \rho(B_{es})$

**CONSTRUCCIÓN DE POLINOMIO**  
 ① Lagrange  $P(x) = \sum_{i=0}^n f(x_i) l_i(x)$  (Forma)  $\oplus$  Newton  $P_n(x) = f(x_0) + f[x_0, x_1](x-x_0) + \dots$   
 $l_i(x) = \prod_{j \neq i} \frac{x-x_j}{x_i-x_j}$  (P.L.)

**VALOR MEDIO INTEGRAL**  
 Si  $f$  es continua en  $[a, b]$  y  $g$  no cambia de signo en  $[a, b] \Rightarrow \exists \xi \in [a, b]$  tal que  $\int_a^b f(x)g(x)dx = f(\xi) \int_a^b g(x)dx$

**NEWTON-COTES** Nodos equidistantes,  $h$  tamaño entre nodos  
 Trapecio  $\rightarrow x_0 = a, x_1 = b, h = b-a, \frac{b-a}{2} (f(x_0) + f(x_1))$  Error  $\frac{(b-a)^3}{12} f''(\xi)$  (Forma)  $\int_a^b f = \frac{h}{2} (f(x_0) + f(x_1)) - \frac{h^3}{12} f''(\xi)$   
 - Tabla 

Nodos	a	b
Poses	0	1

**FORMULA SIMPSON**  $x_0 = a, x_1 = \frac{a+b}{2}, x_2 = b, n=2$  Utiliza P.L. Newton  $f(x_0) = f(x_0), f(x_1) = f(x_1), f(x_2) = f(x_2)$   
 $\int_a^b P_2(x) = \frac{f(x_0) + 4f(x_1) + f(x_2)}{3} h$  - Tabla 

a	$\frac{a+b}{2}$	b
0	1/2	1

 Error  $\frac{f''''(\xi)}{90} h^5$   
 $\int_a^b f = \frac{h}{3} (f(x_0) + 4f(x_1) + f(x_2)) - \frac{f''''(\xi)}{90} h^5$   
 $x_0 = a, x_2 = b, x_1 = x_0 + h = \frac{a+b}{2}, h = \frac{b-a}{2}$   
 • Fin de tipo interpolatorio de  $n+1$  nodos en subintervalos  
 son orden  $n+1$  si  $n+1$  par  
 son orden  $n+1$  si  $n+1$  impar



**COMPUERTAS**

$$\int_a^b f = \sum_{i=1}^N \int_{x_{i-1}}^{x_i} f = \sum_{i=1}^N \sum_{j=0}^N C_{ij} f(x_{ij}) + \sum_{i=1}^N E_i(f)$$

**Teorema valor medio**  $f \in C^1([a,b]) \Rightarrow f(b) - f(a) = f'(\xi)(b-a)$

GRABAR - SHIR

$w_1 = \frac{1}{2}, w_2 = \frac{1}{2}$   
 $w_2 = \frac{1}{2} - \frac{f(w_1, w_2)}{f(w_1, w_2)}$

**Trapezio compuesta**  $[a,b], N = \text{nº intervalos}, h = \frac{b-a}{N} = \text{cte} = \text{long. intervalos}$   $x_i = a + ih$

$$\int_a^b f = \frac{h}{2} (f(a) + 2 \sum_{i=1}^{N-1} f(x_i) + f(b)) - \frac{h^3}{12} (b-a) f''(\xi), \xi \in [a,b]$$

$\frac{(b-a)^3}{12 N^2} f''(\xi) \rightarrow 0, O(1/N^2)$  Precisión 2

**Trapezio corregida compuesta**

$$\int_a^b f = \frac{h}{2} [f(a) + f(b) + 2 \sum_{i=1}^{N-1} f(x_i)] + \frac{h^2}{12} [f'(a) - f'(b)] + \frac{h^4(b-a)}{720} f'''(\xi)$$

$\frac{1}{N} \frac{(b-a)^5}{720} f'''(\xi) = O(1/N^4)$   $\xi \in [a,b]$

**Simpson compuesta**  $[a,b], N = \text{nº intervalos}, h = \frac{b-a}{N}, x_i = a + ih$

$$\int_a^b f = \sum_{i=1}^N \int_{x_{i-1}}^{x_i} f = \sum_{i=1}^N \frac{h}{6} (f(x_{i-1}) + 4f(\frac{x_{i-1}+x_i}{2}) + f(x_i)) - \frac{h^5}{90 \cdot 2^5} (b-a) f^{(5)}(\xi)$$

$\frac{(b-a)^5}{90 \cdot 2^5} \frac{1}{N^4} f^{(5)}(\xi) \rightarrow 0, O(1/N^4)$

**GAUSS**

$n+1$  nodos  $x_i, i=0, \dots, n$   
 $n+1$  coef.  $\lambda_i, i=0, \dots, n$   
 No equidistantes.

$$\int_a^b f \approx \sum_{i=0}^n C_i f(x_i) \quad \int_a^b w(x) f(x) dx = \sum_{i=0}^n C_i f(x_i) + \int_a^b w(x) E(f) dx$$

$\int_a^b w(x) x^k dx = \sum_{i=0}^n C_i x_i^k \rightarrow \text{Orden } 2n+1$

$\sum_{i=0}^n C_i x_i^k = 0, k=0, 1, \dots, n, 2n+1, \dots, 2n+2$

① Paso  $\int_a^b w(x) E(f) dx = \int_a^b w(x) \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \prod_{i=0}^n (x-x_i) dx$

$E(f) = P + E(f) = \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \prod_{i=0}^n (x-x_i)$

$R(x) = \int_a^b w(x) (x-x_i)^{2n+1} \pi(x) dx = 0$

② Cálculo  $B' \perp B = \{1, x, x^2, \dots, x^{n+1}\}$  con  $(f, g) = \int_a^b f(x)g(x)w(x)dx$  de  $B'$  tomo  $w_{n+1}$  y  $P_{n+1} = w_{n+1}$  y tomo  $P_{n+1} = 0$  y calculo sus raíces  $n+1$  distintas y estan en  $[a,b]$ . los nodos  $n+1$  de Gauss  $x_0, \dots, x_n$

③ Error  $\rightarrow$  Polinomio de Hermite  $P_{2n+2} f = P_{2n+1} + E(f)$

$\int_a^b w(x) f(x) dx = \sum_{i=0}^n C_i f(x_i) + \int_a^b w(x) \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \prod_{i=0}^n (x-x_i) dx$

$E(f) = \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \int_a^b w(x) \pi_n^2(x) dx$

$\pi_n^2(x) \geq 0$

$\pi_n^2(x) \geq 0$

$\pi_n^2(x) \geq 0$

**sol. final**  $\rightarrow \int_a^b w(x) f(x) dx = \sum_{i=0}^n C_i f(x_i) + \frac{f^{(2n+2)}(\xi)}{(2n+2)!} \int_a^b w(x) \pi_n^2(x) dx$

$n+1$  nodos  $w(x) \geq 0$

**FORMULA GAUSS**

**continuo** Def:  $f: [a,b] \times \mathbb{R} \rightarrow \mathbb{R}$  Lipschitziana respecto a la segunda variable: ① Si  $\frac{\partial f}{\partial y}(x,y)$   $\exists$ , continua y acotada

$\exists!$  sol  $\Rightarrow f: [a,b] \times \mathbb{R} \rightarrow \mathbb{R}$  continua y Lipschitziana respecto a la 2ª variable  $\Rightarrow$  (P)  $\exists!$  Sol en  $[a,b]$   $y(x) \in C^1([a,b] \times \mathbb{R})$

④ Prob de valor inicial  $\rightarrow$  PVI  $\rightarrow$  EDO con valores inicial (p)  $\begin{cases} y'(x) = f(x, y(x)) \\ y(x_0) = y_0 \end{cases} \forall x \in [a,b]$

⑤ Sistemas Lineales de EDO

$y'_1 = f_1(x, y_1, y_2, \dots, y_n, y_1(x_0) = y_{10}$

$y'_2 = f_2(x, y_1, y_2, \dots, y_n, y_2(x_0) = y_{20}$

$\vdots$

$y'_n = f_n(x, y_1, y_2, \dots, y_n, y_n(x_0) = y_{n0}$

$\rightarrow \bar{y}'(x) = \bar{f}(x, \bar{y})$

$\bar{y}(x_0) = \bar{y}(x_0)$

⑥ Orden de la EDO  $\rightarrow$  Un PVI de orden  $m \Rightarrow$  sistema lineal de dim.  $m$ , de ecuaciones diferenciales ordinarias  $\Rightarrow$

$\Rightarrow$  PVI de orden 1 en forma vectorial  $\Rightarrow y^m(x) = f(x, y(x), y'(x), \dots, y^{(m-1)}(x)) \in [a,b], y(x_0), y'(x_0), \dots, y^{(m-1)}(x_0)$

$z_1(x) = y(x), z_2(x) = y'(x), \dots, z_{m-1}(x) = y^{(m-2)}(x), z_m(x) = y^{(m-1)}(x)$

$z'_1(x) = z_2(x), z'_2(x) = z_3(x), \dots, z'_{m-1}(x) = z_m(x)$

$z'_m(x) = f(x, z_1(x), z_2(x), \dots, z_m(x))$

$z_1(x_0) = z_{10}, z_2(x_0) = z_{20}, \dots, z_m(x_0) = z_{m0}$

Sistema lineal EDO con  $C$  en  $x_0$

**DISCRETO** Métodos de discretización  $\rightarrow$  Dominio  $[a,b]$   $\rightarrow$  malla de tamaño de paso  $h$  o bien  $N = \frac{b-a}{h} = \text{nº de pasos}$

$x_n = x_0 + nh, b-a = N \cdot h$  luego  $h \rightarrow 0 \Rightarrow N \rightarrow \infty$

⑦ Métodos de 1 paso ( $k=1$ )

$y_{n+1} = F(x_{n+1}, x_n, y_n, y'_n)$

$y_0$

$\rightarrow$  Sol  $\begin{cases} \text{Explícitos} \\ \text{Implícitos} \end{cases}$

$\rightarrow$  Evaluación de  $F$  / 1 iteración

$\rightarrow$  1 valor de arranque

$y_n$  sol exacta

Punto fijo  $\Rightarrow F$  contractiva  $\begin{cases} y_{n+1}^{p+1} = F(y_{n+1}^p) \\ y_{n+1}^p \rightarrow y_{n+1} \end{cases}$

$y_{n+1} = F(y_{n+1})$

⑧  $k$  Pasos  $\Rightarrow y_{n+k} = F(x_{n+k}, x_n, y_n, \dots, y_{n+k})$

**Explícitos**

- Evaluación de  $F$  / 1 iteración
- $k$  valores de arranque

**Implícitos**

- Método iterativo / 1 iteración
- $k$  valores de arranque

⑨  $(P_n)$  orden  $p \Leftrightarrow \frac{P_n}{h} = O(h^p)$

⑩  $(P_n)$  consistente  $\Leftrightarrow \frac{P_n}{h} = O(h) \Leftrightarrow (P_n) = O(h)$

⑪ Si  $(P_n)$  estable y de orden  $p$  es  $O(h)$  converge y err  $\rightarrow 0$  a la velocidad  $p \approx \max_{0 \leq n \leq N} |e_n| \approx O(h^p)$

**Teorema**  $\rightarrow$  Sea  $f \in C^1([a,b] \times \mathbb{R}), \phi \in C^p([a,b] \times \mathbb{R} \times [a,b])$

$\phi(x, y, y') = f(x, y)$

$\frac{\partial \phi}{\partial x}(x, y, y') = \frac{1}{2} f'(x, y)$

$\frac{\partial \phi}{\partial y}(x, y, y') = \frac{1}{2} f''(x, y)$

$\frac{\partial \phi}{\partial y'}(x, y, y') = \frac{1}{2} f'''(x, y)$



# Métodos de un paso

② y ③ → Euler y métodos de resolución de PVI

$$\begin{cases} y'(x) = f(x, y(x)) \\ y(x_0) = y_0 \end{cases}$$

$$\int_{x_n}^{x_{n+1}} y' dx = \int_{x_n}^{x_{n+1}} f(x, y(x)) dx \approx \int_{x_n}^{x_{n+1}} f(x, y_n) dx$$

$$y(x_{n+1}) \approx y_{n+1} \Rightarrow y(x_n) \approx y_n$$

\* Imponer igualdad

$$y_{n+1} = y_n + \int_{x_n}^{x_{n+1}} f(x, y_n) dx$$

## Estudio general

$$(P) \begin{cases} y'(x) = f(x, y(x)) & x \in [a, b] \\ y(x_0) = y_0 \end{cases}$$

$$\text{Malla } x_n = a + nh, n = 0, \dots, N$$

$$(P_n) \begin{cases} y_{n+1} = y_n + h \phi(x_n, y_n, h) \\ y_0 \end{cases} \quad n = 0, \dots, N-1$$

$\phi(x, y, h)$  = Función que define el método

\* Estudio Error  $|y_n - y(x_n)| \rightarrow n=0, \dots, N \rightarrow \max |y_n - y(x_n)|$   $0 \leq n \leq N$

\* Bondad del método  $\left\{ \begin{array}{l} \text{Consistencia: Error en la iteración nra} \\ \text{Estabilidad: Influencia/propagación del error} \end{array} \right\}$

\* Velocidad de Convergencia  $\rightarrow$  orden  $(1/N \rightarrow 0, 1/N^2 \rightarrow 0)$

$$\text{Convergencia: } \max_{0 \leq n \leq N} |y_n - y(x_n)| \xrightarrow[N \rightarrow \infty]{} 0$$

**ERROR**  $\rightarrow$  GLOBAL  $\Rightarrow \text{err} = y(x_n) - y_n$

$\rightarrow$  LOCAL  $\Rightarrow$  Error en una iteración  $\rightarrow R_{n+1} = y(x_{n+1}) - [y(x_n) + h \phi(x_n, y(x_n), h)]$

**CONVERGENCIA**  $\rightarrow \max |y(x_n) - y_n| \xrightarrow[h \rightarrow 0]{} 0$  con  $h, y, y'$  fijos

**CONSISTENCIA**  $\rightarrow$  Con ① Si:  $\sum_{n=0}^N |R_n| \rightarrow 0 \Rightarrow \max_{0 \leq n \leq N} |R_n| \xrightarrow[h \rightarrow 0]{} 0$

## ESTABILIDAD

Sea  $\{y_n\}$  Sol de  $y_{n+1} = y_n + h \phi(x_n, y_n, h)$

$\{z_n\}$  Sol de  $z_{n+1} = z_n + h \phi(x_n, y_n, h) + \text{err}$

(P<sub>n</sub>) estable  $\Rightarrow$  Hcte independiente de h

\* Si (P<sub>n</sub>) es estable y consistente  $\Rightarrow$  Converge

**ORDEN**  $\rightarrow$  (P<sub>n</sub>) es de orden p si p es el mayor natural que:

Def:  $f(h) \in O(h^p)$  si  $\frac{f(h)}{h^p} \xrightarrow[h \rightarrow 0]{} 0$

o A h veces de la anterior

UN PASO ORDEN SUPERIOR

① Objetivo  $\rightarrow$  método m-n-1 paso explícito de orden superior

\* **MÉTODO DE TAYLOR**  $\rightarrow$  ①  $y = f(x, y(x)), f \in C^{p-1}, y(x+h) = y(x) + h y'(x) + \frac{h^2}{2} y''(x) + \dots + \frac{h^p}{p!} y^{(p)}(x) + O(h^{p+1})$

$$= y(x) + h \left[ f(x, y(x)) + \frac{h}{2} f'(x, y(x)) + \dots + \frac{h^{p-1}}{p!} f^{(p-1)}(x, y(x)) \right] + O(h^{p+1})$$

**ESTABILIDAD**  $\rightarrow$  (P<sub>n</sub>) estable  $\Leftrightarrow \phi(x, y, h)$  Lipschitziana 2 variable

## RUNGE-KUTTA 4 EVALUACIONES

$\rightarrow$  Comparar estrategias numéricas: Obtener f. i. n. / método de resolución PVI

$$\phi(x, y, h) = \sum_{r=1}^4 C_r k_r(x, y, h)$$

$$\begin{cases} k_1 = f(x, y) \\ k_2 = f(x + \frac{h}{2}, y + \frac{h}{2} f(x, y)) \\ k_3 = f(x + \frac{h}{4}, y + h \sum_{s=1}^2 \frac{b_{3s}}{4} k_s) \\ k_4 = f(x + h, y + h \sum_{s=1}^3 \frac{b_{4s}}{3} k_s) \end{cases}$$

Coef.  $C_r$  elegidos para conv. y orden max

## ESTABILIDAD

$\rightarrow$  f Lipschitziana 2 var  $\Rightarrow$   $k_1 = f$  Lipschit 2 var  $\hat{c}$   $k_2$  Lipch?

$$|k_2(x_1, y_1, h) - k_2(x_2, y_2, h)| = |f(x_1 + \frac{h}{2}, y_1 + \frac{h}{2} f(x_1, y_1)) - f(x_2 + \frac{h}{2}, y_2 + \frac{h}{2} f(x_2, y_2))| \leq |L(y_1 + \frac{h}{2} f(x_1, y_1) - (y_2 + \frac{h}{2} f(x_2, y_2)))| \leq L(|y_1 - y_2| + \frac{h}{2} |f(x_1, y_1) - f(x_2, y_2)|) \leq L(1 + \frac{h}{2} L) |y_1 - y_2| \Rightarrow k_2 \text{ Lipsth}$$

**ORDEN**  $\rightarrow$  PCE = Orden max de Runge-Kutta de Runge-Kutta

• Si  $R = 1, 2, 3, 4 \rightarrow PCE = R$  • Si  $R = 5, 6, 7 \rightarrow PCE = R-1$  • Si  $R \geq 8 \rightarrow PCE = R-2$

R-K2 orden 2 converge  $\begin{cases} c_1 + c_2 = 1 \\ c_2 a_2 = 1/2 \\ c_2 \cdot b_2 = 1/2 \end{cases} \Rightarrow C_2 [a_2 f(x) + b_2 f(y)]$

**CONSISTENCIA** Sea f Lipch... a 2 variable

$$k_r(x, y, 0) = f(x, y), \forall r \Rightarrow \phi(x, y, 0) = \sum_{r=1}^R C_r k_r(x, y, 0) = f(x, y) \sum_{r=1}^R C_r = f(x, y)$$

$$\sum_{r=1}^R C_r = 1 \Rightarrow \text{Consistencia}$$

## EJERCICIOS Y EJEMPLOS

①  $F'(x, y) = f_x + f_y$   $\frac{\partial \phi}{\partial h} = \frac{1}{2} F'(x, y) \Rightarrow$  orden 2 si  $\phi(x, y, 0) = f(x, y) \Rightarrow$  orden 1

①  $\begin{cases} y'(x) = y(x) - y^2(x) \\ y(0) = 1 \end{cases}$   $\Rightarrow$  ②  $\Rightarrow \begin{cases} y'(x) = f(x, y(x), y(x)) \\ y(0) = y_0 \\ y'(0) = y_0 \end{cases}$  sustit.  $y'(0) = y(0) - y^2(0) = 1 - 1 = 0$

derivada  $y''(t) = y'(t) - 2y(t)y'(t) + y(t)$   $\begin{cases} y_1(t) = y(t) \\ y_2(t) = y'(t) \end{cases} \Rightarrow y'_2 = y_2'' + y_1''$

$\bar{y}(t) = (y_1(t), y_2(t))$   $\Rightarrow \bar{y}'(t) = (y_2(t), y_2'(t) - 2y_1(t)y_2(t) + y_1(t))$   $\bar{y}(0) = (1, 0)$



$$\bar{y}_n + 1/2 (y_2^n, y_2^n - 2y_1^n y_2^n + y_1^n) \Rightarrow (y_1^n + 1/2 y_2^n, y_2^n + 1/2 y_2^n - 2y_1^n y_2^n + y_1^n)$$

$$\begin{cases} y_1^{n+1} = y_1^n + z_1^n \\ y_2^{n+1} = y_2^n + z_2^n - 2z_1^n z_2^n + z_1^n \\ y_1^0 = 1 \\ y_2^0 = 0 \end{cases} \Rightarrow y_1^1 = 3/2, y_2^1 = 1/2$$

$$Sol = y(x) = y_1(x) \approx y_1^1 = 3/2$$

$$(P) \begin{cases} y' = x - y & x \in [0, 1], y \in \mathbb{R} \\ y(0) = 1 \end{cases}$$

①  $y' = x - y \rightarrow y' + y = x \rightarrow$  EDO. Lineal de coefici. constantes no homog.

② Sol homog. asociada  $\rightarrow y' + y = 0 \rightarrow \lambda + 1 = 0 \rightarrow \lambda = -1 \Rightarrow e^{\lambda x}$  Sol

③ Sol general de E CDO  $\rightarrow y(x) = \Delta x + B \rightarrow \Delta + \Delta x + B = x \rightarrow$  Sol particular  $\Rightarrow y(x) = x - 1$

$$(P) \begin{cases} y' = x - y \\ y(0) = 1 \end{cases} \quad (E) = \begin{cases} y_{n+1} = y_n + h f(x_n, y_n) \\ y_0 = 1 \end{cases}$$

$$h = 0.2 \Rightarrow N = \frac{b-a}{h} = 5 \Rightarrow \text{Malla } x_0 = 0, x_1 = 0.2, \dots, x_5 = 1$$

$$x_n = a + hn \quad x_n = n \cdot 0.2, n = 0, \dots, 5$$

$$y_{n+1} = y_n + 0.2 f(0.2n, y_n) = y_n + 0.2 (0.2n - y_n) = (0.2)^2 n + 0.2 y_n$$

$$\text{Heam } y_{n+1} = y_n + h \left[ \underbrace{1/2 f(x_n, y_n)}_{C_1} + \underbrace{1/2 f(x_n + h, y_n + h f(x_n, y_n))}_{C_2} \right] \Rightarrow h = 0.2$$

$$\phi = C_1 k_1 + C_2 k_2 / C_1 + C_2 = 1 \Rightarrow \text{orden 1}$$

$$(P_n) \begin{cases} y_{n+1} = y_n + 0.2 \cdot 1/2 (x_n - y_n) + x_n + 0.2 - (0.2 y_n + (0.2)^2 n) = y_n + 0.1 [2(0.2n) - (0.2)^2 n + 0.2 - 1 y_n] = \\ y_0 = 1 \end{cases} = y_n + 0.1 [0.6n + 0.2 - 1 y_n]$$

$$\begin{cases} G(x) = (I - \Delta)x + b \Rightarrow \text{Contrac} \\ G(y) = (I - \Delta)y + b \end{cases}$$

$$\|G(x) - G(y)\| = \|(I - \Delta)x + b - (I - \Delta)y + b\| = \|(I - \Delta)(x - y)\| \leq \underbrace{\|(I - \Delta)\|}_{< 1} \|x - y\|$$

$$\text{⑤ Tiene Sol } y \text{ es } \text{única? } x = \Delta^{-1}b \Rightarrow x^n = G(x^{n-1}) = (I - \Delta)x^{n-1} + b$$

$$x = G(x) \Rightarrow x = (I - \Delta)x + b; \quad x - x = -\Delta x + b; \quad \Delta x = b$$

$$\Delta = M - N \rightarrow \Delta = D - L - U \quad \begin{cases} M = D \\ N = L + U \end{cases}$$

$$M^{-1}N = D^{-1}(L + U) = D^{-1}(D - \Delta) = I - D^{-1}\Delta$$

$$Bw = D^{-1}(D - W\Delta) \quad \text{⑥ } \int_{-1}^1 |x| f(x) dx \approx \Delta_0 f(x_0) + \Delta_1 f(x_1) \quad \begin{cases} \int_{-1}^1 \pi(x) dx = 0 \\ \int_{-1}^1 x \pi(x) dx = 0 \end{cases} \Rightarrow \pi(x) = x^2 - 1/2$$

$$Cw = D^{-1}W\Delta$$

$$B \rightarrow 1, x_1 \quad f(x) = 1 \rightarrow \int_{-1}^1 |x| dx = 1 = \Delta_0 + \Delta_1; \quad f(x) = x \rightarrow \int_{-1}^1 |x| x dx = 0 \rightarrow \Delta_0(-1/\sqrt{2}) + \Delta_1(1/\sqrt{2})$$

$$\int_{-1}^1 |x| f(x) dx \approx 1/2 \{f(-1/\sqrt{2}) + f(1/\sqrt{2})\} \quad \text{⑦ } \log 2 = \int_0^1 \frac{2x}{1+x^2} dx \quad \int_{-1}^1 \frac{|x|}{1+x^2} dx = 2 \int_0^1 \frac{|x|}{1+x^2} dx = \int_0^1 \frac{2x}{1+x^2} dx = \log 2$$

$$\text{GAUSS 3 Puntos } x_0, x_1, x_2 \quad n=2 \Rightarrow \int_a^b f = \sum_{i=0}^2 C_i f(x_i) + \int_a^b \tilde{E}_2(f) dx \rightarrow \text{Exacta para } 1, x, x^2, x^3, x^4, x^5$$

$$\text{① Coeficientes } x_0, x_1, x_2 \rightarrow P_2(x) = 0; \quad P_2(x) = x^3; \quad k = 3, 4, 5$$

$$1/3! \int_a^b P_2(x) \frac{f(x)}{q(x)} dx \rightarrow x_0, x_1, x_2 \text{ raíces de } q(x)$$

$$\text{② Calcular } \int_a^b x^k dx = \sum_{i=0}^2 C_i x_i^k, \quad k = 0, 1, 2 \quad \begin{cases} k=0 \rightarrow b-a = C_0 + C_1 + C_2 \\ k=1 \rightarrow \frac{b^2-a^2}{2} = C_0 x_0 + C_1 x_1 + C_2 x_2 \\ k=2 \rightarrow \frac{b^3-a^3}{3} = C_0 x_0^2 + C_1 x_1^2 + C_2 x_2^2 \end{cases} \Rightarrow \text{Sol } \int_a^b f \approx C_0 f(x_0) + C_1 f(x_1) + C_2 f(x_2)$$